COMPUTATION OF THE PARAMETERS OF A SLOT-EMBEDDED CONDUCTOR USING THE FINITE ELEMENT FORMULATION OF THE IMPEDANCE BOUNDARY CONDITION

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The finite element variational formulation of the impedance boundary condition (IBC) is applied to solve two-dimensional eddy current problems, especially at high frequencies in electrical machines. This formulation is used to compute the ac resistance and the self inductance per unit length of both a reverse ‘T’ slot-embedded conductors and a simple slot-embedded conductor. The proposed IBC formulation is very efficient, because it does not change the sparsity of the finite element global matrix as well as it has minimized the computing cost such as computer memory and central processing unit time. The obtained results of both the finite element method (FEM) and the IBC formulation are compared with published results.

KEYWORDS: eddy currents, FE-formulation, IBC formulation, slot-embedded conductor

1. INTRODUCTION

The main problem when treating high frequency phenomena with the finite element method (FEM) is predominant presence of skin and proximity effects. As a solution to this problem, adaptive mesh generation has been proposed in [1]. But the use of this technique is limited only to quite low frequencies. A successful technique for handling this phenomenon then is the use of the surface impedance concept allowing the extraction from the domain of study of conducting parts [2,3]. Thus the number of nodes of the problem is reduced and the system to be solved becomes smaller.

For eddy current problems, the IBC formulation is attractive because of the elimination of the computation within the conducting medium and because of the avoidance of thin elements when the skin depth is small, such as in high frequency problems. This topic has therefore been of considerable interest to many publishers [1-16].

In [4], the IBC integral equation formulation was derived for solving the two-dimensional (2D) eddy current problem of a conducting cylinder placed in a time-harmonic field. The surface impedance method for 2D and 3D eddy current problems was improved in [6] by using more accurate values of impedance based on the special variation of fields on the surface of conducting regions. An economic three-dimensional (3-D) method using the surface impedance technique [7] was used for solving 3-D coupled electromagnetic and thermal problems. A 2-D finite element formulation of the IBC, based on the variational approach for solving eddy current problems, especially at high frequencies was developed by the author [9]. Based on this formulation, a new boundary elemental matrix (IBC matrix) representing the
general Neumann boundary condition was developed. This formulation was very efficient, because it does not change the sparsity of the finite element global matrix. In addition it has greatly reduced the computing cost such as computer memory and central processing unit time. In [11], the author has successfully applied the developed IBC formulation [9] to compute the 2D eddy current in a solid circular conductor carrying an alternating current. Moreover, the formulation has been used to compute the parameters per unit length of shielded and multiconductor power cables.

In this paper, a two-dimensional of the finite element method (FEM) and the developed FE-formulation of the impedance boundary condition (IBC) based on the variational approach are applied to compute the ac resistance and the self inductance per unit length of both a reverse ‘T’ slot-embedded conductors and a simple slot-embedded conductor. The obtained results of the FEM are compared to published results [14]. Therefore, the obtained IBC results are compared to the results of the tested FEM.

2. THE FIELD EQUATIONS

In terms of the time-harmonic magnetic vector potential $A$, the differential equation which governs the two-dimensional eddy current problem is given by

$$ \frac{1}{\mu} (\nabla^2 A) = -J_s + j\omega \sigma A $$

where $J_s$ is the unknown time harmonic source current density and $\mu$, $\omega$ and $\sigma$ are the permeability, angular frequency and conductivity respectively. The total current density in the conductor is given by

$$ J = J_s + J_e = J_s - j\omega \sigma A $$

Where $J_e$ is the eddy current density and both $J_s$ and $A$ are unknowns and must be found. For our own problem, the boundary conditions shown in Fig. 1, are defined as:

$$ A = A(x, y) \quad \text{on} \quad C_1 $$

$$ \frac{\partial A}{\partial n} = 0 \quad \text{on} \quad C_2 $$

$$ \frac{\partial A}{\partial n} = -\gamma A \quad \text{on} \quad C_3 $$

Where $\gamma$ is the propagation constant and is defined as

$$ \gamma = \sqrt{j\omega \mu \sigma} $$

3. THE IBC CONCEPT

For a time-harmonic electromagnetic field incident on a conducting linear medium, the tangential components of the electric field $E$ and the magnetic field $H$ inside the conductor and on its surface are related to each other [1], except at (or near) the corners, by

$$ \vec{n} \times \vec{E} = \vec{Z}_s \hat{n} \times (\vec{n} \times \vec{H}) $$
COMPUTATION OF THE PARAMETERS OF A SLOT-EMBEDDED ...

Fig. 1 solution domain for 2D eddy current problem

where \( n \) is the unit vector out of the conductor and a time dependent is assumed. The surface impedance, \( Z_s \), of an infinite conducting half space plane is given by

\[
Z_s = \frac{1 + j}{\delta\sigma} \tag{8}
\]

where \( \delta \) is the electromagnetic penetration depth and is defined as

\[
\delta = \sqrt{\frac{2}{\omega\mu\sigma}} \tag{9}
\]

After rearranging Eqs. (7) through (8), we obtain an equation similar to Eq. (5). This means that the IBC approximation takes the same form of the general Neumann boundary condition.

4. THE FE-IBC FORMULATIONS

4.1 The Fe-Variational Formulation

The formulation and solution of eddy current problems has been traditionally regarded as one of the more difficult areas of electromagnetic. Using the integro-differential approach [14], both the magnetic vector potential (m.v.p.) \( A \) and the source current density \( J_s \) are treated as unknowns and the classical diffusion Eq. (1) is complemented with Eq. (2)

\[
I = I_s + I_e = \iint J_s \, ds - j\omega\sigma \iiint A \, ds \tag{10}
\]

where \( I, I_s, \) and \( I_e \) are the total current, the total source current and the total eddy current respectively. Hence \( J_s \) can be expressed as

\[
J_s = I/a + j\omega\sigma A \iiint A \, ds \tag{11}
\]

Substituting Eq. (11) into Eq. (1), we can obtain

\[
\frac{1}{\mu}(\nabla^2 A) - j\omega\sigma A + j\omega\sigma A \iiint A \, ds = -\frac{I}{a} \tag{12}
\]
The only unknown in Eq. (12) is magnetic vector potential (m.v.p.) \( A \). It can be shown that the m.v.p., \( A \) that satisfies Eqs. (2), (3) and (12), also minimizes the functional \( F(A) \) as

\[
F(A) = \int_{R} \left[ \frac{1}{\mu} \left( \frac{\partial A}{\partial x} \right)^2 + \left( \frac{\partial A}{\partial y} \right)^2 \right] + j \frac{\omega \sigma}{2} A^2 - \left( \frac{I}{a} + \int_{R} dA \right) A dx dy
\]

The variational principle on which we can base the derivation of the elemental equations is

\[
\left( \frac{\partial F}{\partial A_m} \right)_{m=i,j,k} = 0
\]

The solution region \( R \), is shown in Fig. 1, is subdivided into triangular elements. After minimization of the functional \( F(A) \) (Eq.13), we can finally obtain the following set elemental matrix as

\[
\]

where the elemental matrices \( [S]^{(e)} \), \( [T]^{(e)} \) and \( [I]^{(e)} \) are given in the Appendix. The elemental matrix \( [C]^{(e)} \) consists of identical rows made up of Newton-cotes quadrature weight \([18]\). The elemental matrix \( [T_D]^{(e)} \) is obtained in \([11]\) and is given in the Appendix. By extending Eq. (15) to each of the triangular subdivisions shown in Fig. 1, the final global matrix equations are obtained in the form

\[
[S] [A] + [T] [A] - [T_D] [C] [A] = [I]
\]

### 4.2 The Ibc Formulation

It can be shown that the m.v.p., \( A \) that satisfies Eqs. (2) through (4) and Eq. (12), also minimizes the functional \( F(A) \) as

\[
F(A) = \int_{R} \left[ \frac{1}{\mu} \left( \frac{\partial A}{\partial x} \right)^2 + \left( \frac{\partial A}{\partial y} \right)^2 \right] + j \frac{\omega \sigma}{2} A^2 - \left( \frac{I}{a} + \int_{R} dA \right) A dx dy
\]

Substituting from Eq. (12) by the current density \( J_s \) into Eq. (17), we obtain

\[
F(A) = \int_{R} \left[ \frac{1}{\mu} \left( \frac{\partial A}{\partial x} \right)^2 + \left( \frac{\partial A}{\partial y} \right)^2 \right] + j \frac{\omega \sigma}{2} A^2 - \left( \frac{I}{a} + \int_{R} J_s A \right) dx dy
\]

\[
+ \int_{R} \frac{1}{\gamma} A^2 dC_3
\]

\[
(18)
\]
The variational principle on which we can base the derivation of the elemental equations is

$$
\left( \frac{\partial F}{\partial A_m} \right)_{m=i,j,k} = 0
$$  (19)

After minimization, the functional $F(A)$ (Eq. 18), the following set of the elemental equations can be finally obtained as:

$$
$$  (20)

The matrix $[T_B]^{(e)}$ is the IBC matrix which is obtained by the author [9] as

$$
[T_B]^{(e)} = l_{ij}\gamma
\begin{bmatrix}
\frac{1}{3} & \frac{1}{6} & 0 \\
\frac{1}{6} & \frac{1}{3} & 0 \\
0 & 0 & 0
\end{bmatrix}
$$  (21)

Where $l_{ij}$ is the boundary segment length as shown in Fig. 1. By extending Eq. (20) to each of the triangular subdivisions shown in Fig. 1, the final global matrix equations are obtained in the form

$$
[S][A]+[T][A]-[T_D][C][A]+[T_B][A]=[I]
$$  (22)

### 5. PARAMETERS COMPUTATION

The electrical parameters, i.e. the ac resistance and the self inductance per unit length for slot-embedded conductors can be obtained using the following methods:

#### 5.1 The Energy Method

The energy-related quantities such as loss density and stored magnetic energy are used to compute the ac resistance and the self inductance per unit length. The loss density for a conductor is given by the function $u(x, y)$ as

$$
u(x, y) = \frac{|J(x, y)|^2}{\sigma}
$$  (23)

where the total current density may be obtained as

$$J(x, y) = J_s + J_e(x, y) = \frac{I_s}{a} - j\omega A(x, y)
$$  (24)

The total losses per unit length are obtained as

$$U = \iint u(x, y) dx dy
$$  (25)

The ac-dc loss ratio can be computed as

$$ac-dc\ loss\ ratio = \frac{U}{U_{dc}}
$$  (26)

where the dc losses per unit length of the conductor are given by
\[ U_{dc} = |I|^2 R_{dc} = \frac{|I|^2}{\sigma a} \]  

where \( a \) is the conductor area. The ac losses per unit length of the conductor are given by

\[ U = |I|^2 R \]  

Where \( R \) is the ac resistance per unit length. The self inductance of a conductor per unit length can be obtained from

\[ W = \frac{1}{2} L |I|^2 \]  

where \( W \) is the magnetic stored energy which it can be obtained per unit length of a conductor as

\[ W = \text{Re}\left[ \frac{1}{2} \iint A(x, y) - J_s^*(x, y) dxdy \right] \]  

Using Eqns. (24), (29) and (30), the self inductance per unit length can be obtained as

\[ L = \frac{1}{|I|^2} \text{Re}[J_s^* \iint A(x, y) dxdy] \]  

5.2 The Voltage Drop

The source current density for each conductor can be obtained as

\[ J_s = \frac{I_s}{a} \]  

where \( a \) is the cross-sectional area of the conductor, and the current density \( J_s \) is obtained from Eq. (1). The voltage drop per unit length of the conductor is obtained as

\[ V = \frac{J_s}{\sigma} \]  

The impedance per unit length of the conductor can be computed as

\[ Z = \frac{V}{I} \]  

The real part of \( Z \) is the ac resistance per unit length and the imaginary part is the reactance per unit length.

6. NUMERICAL RESULTS

In this paper, both the FE-formulation and the IBC formulation are applied to compute the electrical parameters, i.e. the ac resistance and the self inductance per unit length for both a reverse ‘T’ slot-embedded conductor and a simple slot-embedded conductor.

6.1 THE REVERSE ‘T’ SLOT-EMBEDDED CONDUCTOR

In this paper, the results of the ac resistance in a reverse ‘T’ slot-embedded conductor is computed using the developed FE program based on the FE-variational formulation.
and is tested by the published results [14]. The FE formulation gives accurate results specially at low frequencies. Then, the results of the present IBC formulation for this model are compared to the results of the tested FE-formulation. This FE-model is discretized into 216 triangular elements and 135 nodes and the boundary conditions (Eqs. (3) and (4)) are also considered as shown in Fig. 2. The FE program solved 128 m.v.p. unknowns for this model. The obtained results of the ratio $R_{AC}/R_{DC}$ are plotted against Dwight’s parameter D, and compared to the published results [14]. These results are found to be in good agreement with the published results as shown in Fig. 3.

Therefore, the present results of the IBC model are compared to the results of the tested FE-program based on the FE-variational formulation. The IBC model shown in Fig. 4 is discretized into 100 triangular elements and 87 nodes and the boundary conditions (Eqs. (3) - (5)) are also considered as shown in Fig. 4. The discretization of this model is limited to only one layer inside the conductor besides layers that represent the free space external region. The developed IBC computer program solved 49 m.v.p. unknowns for this model. The results of the ac resistance, $R$ and the self inductance $L$ per meter which are obtained using the developed IBC formulation were found to be in good agreement with the FE results especially at high frequencies as shown in Table 1 and Table 2. A comparison of computational requirements for the present IBC formulation and the FE-formulation are shown in Table 3. The obtained results are carried out with the total current $I$ equal to 1 A.

![Fig. 2. Reverse ‘T’ Slot-embedded conductor (FEM model) (geometry and dimensions are in millimeters)](image)
Fig. 3 AC-DC resistance ratio versus Dwight’s parameter $D$ for reverse ‘T’ Slot-embedded conductor. ($R_{DC} = 0.731108 \times 10^{-4} \Omega/m$, $D = \sqrt{\frac{2\mu f}{R_{DC}}}$)

![Image](https://via.placeholder.com/150)

Fig. 4. Reverse ‘T’ Slot-embedded conductor (IBC model) (geometry and dimensions are in millimeters)

<table>
<thead>
<tr>
<th>f (c/s)</th>
<th>60</th>
<th>100</th>
<th>200</th>
<th>300</th>
</tr>
</thead>
<tbody>
<tr>
<td>FEM</td>
<td>$1.78 \times 10^{-4}$</td>
<td>$1.8 \times 10^{-4}$</td>
<td>$1.81 \times 10^{-4}$</td>
<td>$2.414 \times 10^{-4}$</td>
</tr>
<tr>
<td>Present IBC</td>
<td>$1.95 \times 10^{-4}$</td>
<td>$1.98 \times 10^{-4}$</td>
<td>$2.11 \times 10^{-4}$</td>
<td>$2.32 \times 10^{-4}$</td>
</tr>
</tbody>
</table>
6.2 A Simple Slot-Embedded Conductor

The FEM model is discretized into 180 triangular elements and 112 nodes and the boundary conditions (Eqns. (3) and (4)) are also considered as shown in Fig.5a. The FE program solved 105 m.v.p. unknowns for this model. The present IBC results for the IBC model shown in Fig. 5b are compared to the results of the tested FE-program based on the FE-formulation.

The IBC model shown in Fig. 5b is discretized into 104 triangular elements and 86 nodes and the boundary conditions (Eqs (3) - (5)) are also considered (Fig.5b). The discretization of this model is limited to only one layer inside the conductor besides layers that represent the free space external region. The developed IBC computer program solved 52 m.v.p. unknowns for this model. The results of the resistance, R and the self inductance L per meter which are obtained using the developed IBC formulation were found to be in close agreement with the FE results especially at high frequencies as shown in Table 4 and Table 5. A comparison of computational requirements for the present IBC formulation and the FE-formulation are shown in Table 6. The obtained results are carried out with the total current I equal to 1 A.
7. CONCLUSIONS

The present work proposes an application of the finite element variational formulation of the impedance boundary condition (IBC) for solving two-dimensional eddy current problems, especially at high frequencies in electrical machines. Both the finite element method (FEM) and the IBC formulation are used to compute the ac resistance and the self inductance per unit length of both a reverse ‘T’ slot-embedded conductors and a simple slot-embedded conductor. The main advantage of this IBC formulation is that the FE-global matrix is still banded and symmetric. Moreover, this formulation has greatly reduced the number of unknowns of the problem. So, the formulation has minimized the computing cost such as computer memory and central processing unit time, since it has greatly reduced the number of nodes and the number of unknowns of the problem. The obtained results of both the finite element method (FEM) and IBC formulation are compared to published results.

8. REFERENCES


9. Appendix

The previously published elemental matrices \([S]^{(e)}, [T]^{(e)}, [I]^{(e)}\) are given in [15] as

\[
[S]^{(e)} = \frac{1}{4\mu\Delta} \begin{bmatrix}
(b_j b_j + d_j d_j) & (b_j b_j + d_j d_j) & (b_j b_j + d_j d_j) \\
(b_j b_j + d_j d_j) & (b_j b_j + d_j d_j) & (b_j b_j + d_j d_j) \\
(b_k b_k + d_k d_k) & (b_k b_k + d_k d_k) & (b_k b_k + d_k d_k)
\end{bmatrix}
\]

Where

\[
b_i = (y_j - y_k),\quad d_i = (x_k - x_j)
\]

and so on. where \(\Delta\) is the area of the triangular element, (e) shown in Fig. 1, the remaining constants of matrix \([S]^{(e)}\) are given in [15]. The remaining matrices are given as:

\[
[T]^{(e)} = \frac{j\omega\sigma\Delta}{12} \begin{bmatrix}
2 & 1 & 1 \\
1 & 2 & 1 \\
1 & 1 & 2
\end{bmatrix}
\]

and

\[
[I]^{(e)} = \frac{J\Delta}{3} \begin{bmatrix}
1 \\
1 \\
1
\end{bmatrix}
\]

The elemental matrix \([T_D]\) is given in [11], where \(a\) is the conductor area.